





















































































CATEGORY	FEATURES			
CORE FEATURES	NOTIFICATION FILTERS			
	RTLS INTEGRATION			
EXPLORER	3D WORLD REPRESENTATION			
	VARIABLE FILTERS FOR DISPLAYING AGV FLEETS			
FLEET MANAGER	SELECT A SPECIFIC AGV FOR A MISSION			
	SMOOTH TRANSITION BETWEEN DRIVE STEPS			
	MISSION CANCELLATION AFTER THE FIRST STEP (VIA API)			
	MANUAL MISSION COMPLETION			
	MAP IMPORT INTO FM			
	SUPPORT FOR MISSION EXPANSION			
	TIME LOCK			
	SPACE AWARENESS			
	DYNAMIC SPACE AWARENESS			
	CONTINUOUS CHARGING (BM)			
	PATH PENALTY OPTIMIZATION			
MAP EDITOR	MAP EDITOR			
	EDGE DIVISION BASED ON MAXIMUM DISTANCE			
	COLLABORATION MODE FOR THE EDITOR			
	TRACK ZONING			
	IMPORT CONTOURS INTO THE MAP EDITOR			
	AGV DOWNHILL DRIVING (SLOPE DESCENT)			
	SETTING MAXIMUM SPEEDS FOR AGVS PER EDGE			
MONITORING	REMOVING AGVS WITH ACTIVE MISSIONS FROM THE MAP			
	AGV PARAMETER CONFIGURATION			
	MISSION PRIORITY			
	ETA (ESTIMATED TIME OF ARRIVAL)			
	HISTORY PLAYBACK			
	CUSTOM BUSINESS-LOGIC MISSIONS	