

# WEWO L-Cart Datasheet



Find comprehensive details and specifications of the WEWO L-Cart in the booklet.

www.scanlox.com



The WEWO L-Cart is a powerful AGV designed for lifting and transporting products smoothly. Featuring a unique lift module and a vertical front section, the L-Cart can navigate both at ground level and at height, compared to the WEWO Move AGVs.

The L-Cart lifts products independently by positioning itself beneath them, then transports them to the desired location, making it ideal for environments requiring efficient, automated material handling.



## Performance Data

50 mm 600 kg 1,6 m/s

Max. Lifting Height Max. Lifting Weight Max. Speed

#### **Dimensions**

1.613 x 800 x 2.340 mm (L x W x H)

## **Specifications**

Natural Navigation - Top RAL7016, RAL1007

**Powder Coating** 

Certification

**CE Standard** 

Navigation Method

Closed Lift System

Lift System

Lithium-Ion

Battery

Specification

Cages / Rollercages

Dimensions max

According to requirement

Exeptions

Carriers with closed bottom

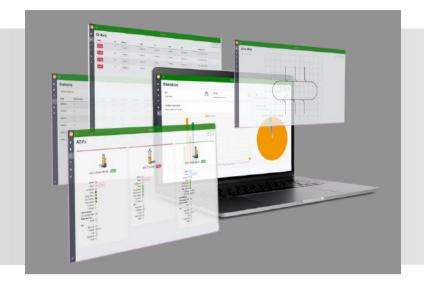
Other types of carriers - inquiry to supplier

NB: The vehicle is not limited by plastic wrap on the pallet's foot

Carrier Types



# Fleetmanagement & WMS Application



The Fleet Management Software & MES provides all the essential tools to efficiently manage warehouse and production environments. It seamlessly controls multiple AGVs within the same space, optimizing workflow and minimizing disruption.



#### Task Management

Assign, monitor, and prioritize tasks effortlessly.



#### Alarm & Traffic Management

Prevent bottlenecks and ensure smooth operation.



#### **Deadlock Prevention**

Optimize vehicle paths for continuous flow.



#### **System Integration**

Connects seamlessly with MES, ERP, and other enterprise systems.

For businesses without an existing warehouse management system, the WEWO WMS application offers a complete solution.

Designed to integrate seamlessly with the Fleet Management Software, this system enables full control over inventory and logistics.



### **Comprehensive Product Tracking**

Monitors product positions and data in real time.



#### Seamless Integration

Connects with production lines, machines, and delivery stations.

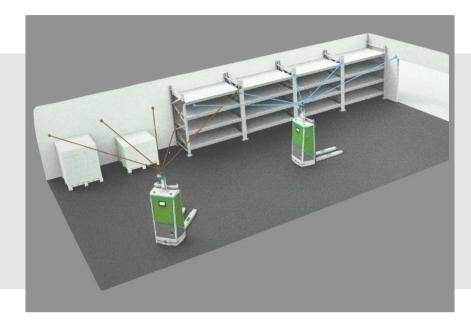


#### **User Role Management**

Ensures secure and efficient system access based on defined permissions.



# **Navigation Method**



The L-Cart utilizes natural navigation with top-mounted laser scanning to ensure precise and reliable movement.

Equipped with a high-accuracy laser scanner, the system continuously maps the environment, detecting reflectors to determine the vehicle's exact position.

# **Key Advantages**

# **Highly Accurate Positioning**

Advanced laser scanning provides precise location tracking.

# **Long-Range Detection**

The scanner covers a wide area, ensuring efficient navigation.

# Reliable in Dynamic Environments

Detects across flexible objects.

# **Enhanced Stability**

Dead reckoning technology further refines positioning for consistent movement.



# Safety & Scanners



The AGVs are equipped with advanced safety systems designed to protect employees, infrastructure, and the robots themselves.

They comply with international standards such as **ISO 3691-4** and **EN1525**.



# **Energy Management**

The AGVs feature automatic charging, eliminating the need for manual intervention. When the battery reaches a minimum level, the AGV completes its current task and automatically navigates to an available charging station.

With this intelligent charging system, the AGVs remain operational with minimal interruptions, ensuring maximum efficiency in warehouse and production environments.

## **Key Advantages**

## **Seamless Integration**

AGVs recharge without disrupting operations.

## **Automated Docking**

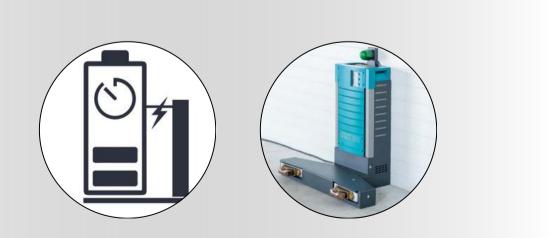
The integrated power collector ensures precise contact with the charging station.

# **Programmable Charging Levels**

Adjust battery thresholds to optimize uptime and efficiency.

#### **Minimal Downtime**

Once charged, the AGV automatically resumes its next task.





# **Dimensions**

